

# Stat 88: Probability & Statistics in Data Science



THE AUTHOR OF THE WINDOWS FILE COPY DIALOG VISITS SOME FRIENDS.

<https://xkcd.com/612/>

## Lecture 13: 3/1/2022

Finishing up indicators, Unbiased estimators, Conditional expectation

Sections 5.3, 5.4, 5.5

# Agenda

- Finish up examples of computing expectations using indicators
- 5.4
  - Unbiased Estimators
- 5.5
  - Conditional expectation
- 5.6
  - Introduce expectation by conditioning

## Example 1

We have a box with balls that are red, white, or blue, with 35% being red, 30% being white, and 35% blue. If we draw  $n$  times with replacement from this box, what is the expected number of colors that *don't* appear in the sample?

## Example 2

An instructor is trying to set up office hours during RRR week. On one day there are 8 available slots: 10-11, 11-noon, noon-1, 1-2, 2-3, 3-4, 4-5, and 5-6. There are 6 GSIs, each of whom picks one slot. Suppose the GSIs pick the slots at random, independently of each other. Find the **expected number of slots that *no* GSI picks.**

## Example 3

A building has 10 floors above the basement. If 12 people get into an elevator at the basement, and each chooses a floor at random to get out, independently of the others, at **how many floors do you expect the elevator to make a stop** to let out one or more of these 12 people?

## 5.4 Unbiased Estimators

- We showed the linearity of expectation earlier:  $E(\mathbf{a}X + \mathbf{b}) = \mathbf{a}E(X) + \mathbf{b}$
- We often want to estimate a *population parameter*: some fixed number associated with the population, possibly unknown
- A statistic is any number that is computed from the data sample. Usually we use a *random sample*.
- Note that the parameter is *constant* and the statistic is a *random variable*.
- We will use a *statistic* to *estimate* (guess at the value of; approximate) the parameter. It is called an *estimator* of the parameter.
- If the expectation of the statistic is the parameter that it is estimating, we call the statistic an *unbiased estimator of the parameter*.

## An example of an unbiased estimator: $E(\bar{X}) = \mu$

- Let  $X_1, X_2, \dots, X_n$  be our random sample, and the sample mean is  $\bar{X}$
- $\bar{X}$  is computed from the sample and will change depending on the sample values, so is a *random variable*.
- If  $X_1, X_2, \dots, X_n$  which are random draws from the population, all have expectation  $\mu$ , what is the expectation of  $\bar{X}$  ?

# Understanding unbiased parameters

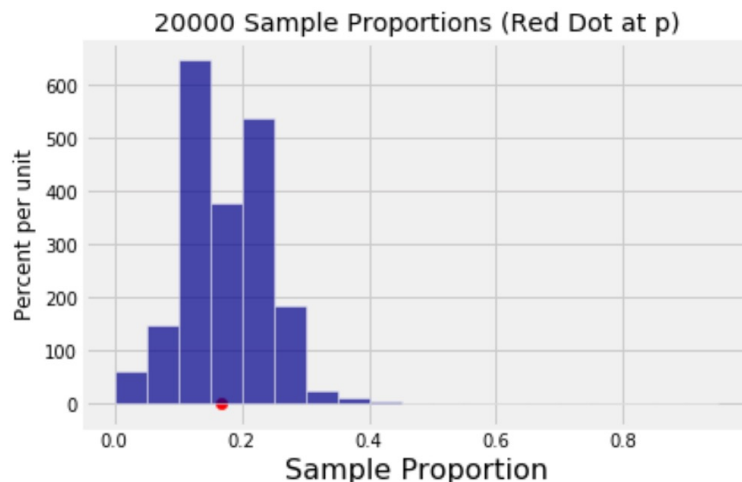
- Let  $X_1, X_2, \dots, X_n$  be random draws from the population, all have expectation  $\mu$ .
- If an estimator  $S$  is unbiased, then **on average**, it is equal to the number it is trying to estimate
- Which of the following are unbiased estimators of  $\mu$ ?
  - (a)  $X_{15}$
  - (b)  $\frac{X_1 + X_{15}}{15}$
  - (c)  $\frac{X_1 + 2X_{100}}{3}$
  - (d) How to make an biased estimator unbiased?
  - (e) If  $X_1$  is unbiased, why bother taking the mean? Why not just use  $X_1$ ?



# Understanding unbiased parameters

## A special estimator: The sample proportion $\hat{p}$

- Usual special case of population binary outcomes represented by 0 and 1
- Sum of draws = # of 1s that are in the sample (sample sum)
- Sample mean = proportion of 1s in sample
- Consider a population of 0s and 1s, and draw  $n$  times from this population, **with** replacement:  $X_1, X_2, \dots, X_n$  are the draws, note that each of the  $X_k$  are Bernoulli or indicator random variables, with parameter  $p$  where  $p$  = proportion of 1s in the population.
- Note that the population mean  $\mu = p$  and the sample mean  $\bar{X} = \hat{p}$ , and  $\bar{X}$  is an unbiased estimator of  $p$



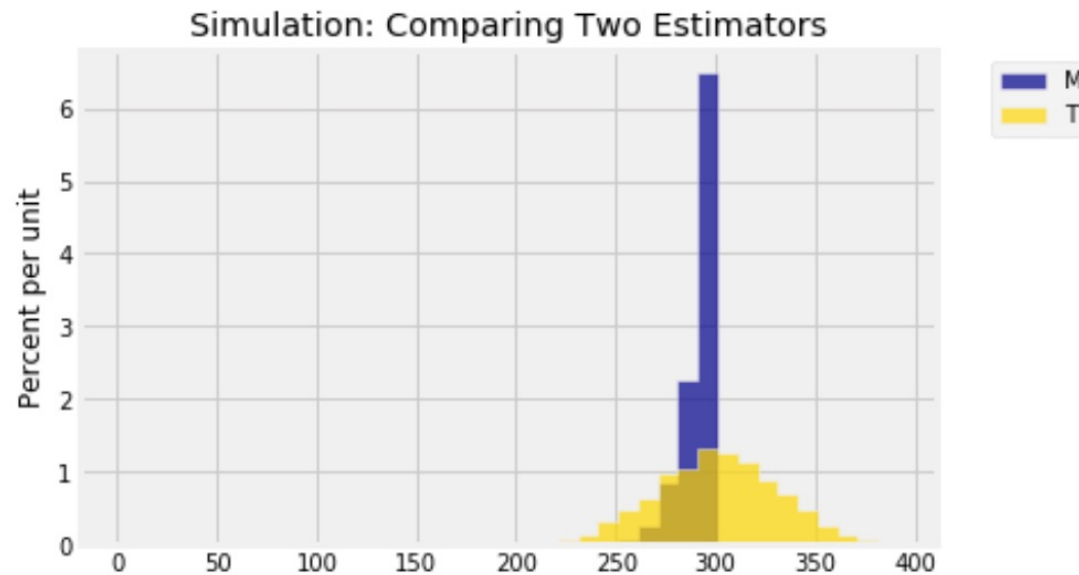
0.1666667  
0.2666667  
0.2333333  
0.2000000  
0.1000000

## Estimating the largest possible value

- $X_1, X_2, \dots, X_n$  are drawn at random with replacement from  $\{1, 2, \dots, N\}$ . That is, they are independent and identically distributed random variables with the discrete uniform distribution on  $1, 2, \dots, N$ .
- We want to estimate  $N$  using an unbiased estimator. Does the sample mean work?

## Comparing two estimators: T and M (max sample value)

- Let  $X_1, X_2, \dots, X_n$  be as earlier, and let  $M = \max\{X_1, X_2, \dots, X_n\}$ . Below are histograms for  $M$  and  $T = 2\bar{X} - 1$ , from simulations assuming that  $N=300$  and that the sample size is 30 (5,000 repetitions, computing T, M each time).



- pros & cons for M
- pros & cons for T

## Example: (5.7.11)

A data scientist believes that a randomly picked student at his school is twice as likely not to own a car as to own one car. He knows that no student has three cars, though some students do have two cars. He therefore models the probability distribution for the number of cars owned by a random student as follows. The model involves an unknown positive parameter  $\theta$ .

# of cars	0	1	2
Probability	$2\theta$	$\theta$	$1 - 3\theta$

- (a) Find  $E(X)$ , where  $X$  is the number of cars owned by a randomly selected student (the pmf is above).
- (a) Let  $X_1, X_2, \dots, X_n$  be the numbers of cars owned by  $n$  random students picked independently of each other. Assuming that the data scientist's model is good, use the **entire sample** to construct an unbiased estimator of  $\theta$ .



## Conditional Distributions: An example

- Suppose we have two rvs,  $V$  and  $W$ , and we have the joint dsn for these two rvs. Suppose we fix a value for  $W$  - call this value  $w$  - and compute, for each value of  $V$ , the probability  $P(V = v | W = w)$ , then this set of probabilities, which will form a pmf, is called the **conditional distribution of  $V$ , given  $W = w$** .
- Let  $X$  and  $Y$  be iid rvs with the distribution described below, and let  $S = X + Y$ :

$x$	1	2	3
$P(X = x)$	1/4	1/2	1/4

- Let's write down the **joint distribution** of  $X$  and  $S$ , and then compute the conditional dsd for  $X$

# Conditional distributions: An example



# Expectation by Conditioning

- In the example we just worked out, once we fix a value  $s$  for  $S$ , then we have a distribution for  $X$ , and can compute its expectation using that distribution that depends on  $s$ :  $E(X | S = s) = \sum x \cdot P(X = x | S = s)$ , with the sum over all values of  $X$ .
- Note that  $E(X | S = s)$  depends on  $S$ , so it is a *function* of  $s$ . We can think of  $E(X | S)$  as a rv as it is a function of  $s$  and has a probability distribution on its values.
- This means that if we want to compute  $E(X)$ , we can just take a weighted average of these conditional expectations  $E(X | S = s)$ :

$$E(X) = \sum_s E(X | S = s) P(S = s)$$

- This is called the *law of iterated expectation*

## Law of iterated expectation

- Note that  $E(X | S = s)$  is a function of  $s$ . That is, if we change the value of  $s$  we get a different value. (It is not a function of  $x$ , though since the  $x$  is summed out .)
- Therefore, we can define the function  $g(s) = E(X | S = s)$ , and the random variable  $g(S) = E(X | S)$ .
- In general, recall that  $E(g(S)) = \sum_s g(s)f(s) = \sum_s g(s)P(S = s)$ .
- How can we use this to find the expected value of the rv  $g(S)$ ?

## Examples from the text: Time to reach campus

- 2 routes to campus, student prefers route A (expected time = 15 minutes) and uses it 90% of the time. 10% of the time, forced to take route B which has an expected time of 20 minutes. What is the expected duration of her trip on a randomly selected day?

## Catching misprints

- The number of misprints is a rv  $N \sim Pois(5)$  dsn. Each misprint is caught before printing with chance 0.95 independently of all other misprints. What is the expected number of misprints that are caught before printing?